

1 **Amendment to the Specification**

2 **In the Specification:**

3 Please amend the specification as follows:

4 On Page 1, the paragraph beginning at line 14 should be replaced with the following.

5 The use of simulated physiological structures for training medical students and providing skill
6 training for practicing physicians is widespread. Although cadavers have traditionally been
7 beneficially employed for this purpose, cadavers are not always readily available and are not well
8 suited for all types of training.

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10 On Page 2, the paragraph beginning at line 1 should be replaced with the following.

11 The need for such simulators should not be underestimated, because they can provide
12 valuable training that will lead to more effective treatment of patients. For example, medical
13 personnel who administer emergency trauma care can greatly benefit from the training achieved
14 using a simulated physiological structure. Training in administering trauma surgical procedures,
15 which include those procedures that are usually performed on a person who has experienced some
16 form of severe and often ~~life-threatening~~ life-threatening injury, is particularly beneficial. Such
17 procedures may aid in the diagnosis of a condition, or may provide immediate life-saving care until
18 more complete medical treatment is available. The procedures may include clearing a blocked
19 airway or draining accumulations of fluids from internal organs. While appearing to be simple
20 procedures, if these procedures are performed improperly, the result can worsen the patient's
21 condition, placing the patient at an even greater peril of death. By their nature, trauma procedures are
22 usually performed under emergency conditions in which the person administering the care is under
23 time-related stress. It is therefore useful to provide training methods and apparatus to fully prepare
24 students and physicians in these procedures, so that they can be performed without delay, under
25 stressful conditions.

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27 On Page 6, the paragraph beginning at line 18 should be replaced with the following.

28 Some embodiments further include a sensor coupled with the evaluation circuit, and the
29 evaluation circuit is configured to provide the signal when the sensor indicates a change in a physical
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1 property has been detected. Beneficial sensors will include temperature sensors and chemical
2 sensors.

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4 On Page 7, the paragraph beginning at line 7 should be replaced with the following.

5 In another embodiment, the conductive elastomer is configured to achieve a touch sensitive
6 circuit. Touch sensitive circuits can be achieved using circuits sensitive to changes in temperature,
7 resistance, capacitance,[[.]] and radio reception. Some touch sensitive circuits can be configured to
8 be pressure sensitive as well, such that a magnitude of pressure applied can be determined.

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10 On Page 11, the paragraph beginning at line 15 should be replaced with the following.

11 FIGURES 10A-10D schematically ~~illustrates~~ illustrate embodiments of evaluation circuits in
12 accord with the present invention;

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14 On Page 11, the paragraph beginning at line 19 should be replaced with the following.

15 FIGURES 12A-12D schematically ~~illustrates~~ illustrate different embodiments for processing
16 an indication from one of the evaluation circuits of FIGURES 10A-10D and 11A-11E;

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18 On Page 14, the paragraph beginning at line 14 should be replaced with the following.

19 Conductive elastomer-based evaluation circuits incorporated into simulated physiological
20 structures can be used in a variety of different ways. Three significant uses include collection of data
21 which is stored for later use, collection of data to be processed to provide some contemporaneous
22 feedback (such as a visual or an audible indication that a procedure has been performed correctly or
23 incorrectly, provided to a trainee, a proctor, or both), and collection of data which is analyzed and
24 may be used to trigger a simulated physiological response in the simulated physiological structure
25 (i.e. a change in a simulated heartbeat, a simulated muscular response, a change in a simulated
26 respiratory rate, etc., implemented by controlling a servo or pump). In a relatively simple
27 implementation, the electrical signal obtained from a conductive elastomer-based evaluation circuit is
28 used to provide simple feedback, such as lights that turn on or off, and/or the activation of aural or
29 verbal prompts or cues. In some implementations the metric is simply whether a current is flowing
30 through the circuit. More complex circuits can be configured to determine a position of a simulated

1 medical instrument (such as a needle, a catheter, an endoscope, or other tool) during each phase of a
2 simulated procedure, to respond to touch, to measure pressure (useful for determining if the force
3 applied by a trainee in ~~handling~~ handling a structure such as an organ is appropriate), and/or to
4 measure impedance changes throughout a circuit. The use of appropriate sensors in a conductive
5 elastomer-based evaluation circuit will enable changes in physical properties of the model to be
6 evaluated. For example, some medical procedures involve the application of chemicals (i.e., drugs),
7 heat, cold, and/or electromagnetic radiation to tissue or other physiological structures. Appropriate
8 sensors can be incorporated into conductive elastomeric-based evaluation circuits so that feedback
9 relating to the physical property change can be gathered. The electrical signal from the evaluation
10 circuit can be manipulated and analyzed by logical processing elements, such as computers. Using a
11 computer enables data provided by such evaluation circuits to be immediately processed and
12 displayed, immediately processed but stored for later use, stored for later processing, compared to
13 similar data, electronically distributed to other users in a network, or any combination thereof.

14
15 On Page 19, the paragraph beginning at line 10 should be replaced with the following.

16 Beginning with the uppermost and outermost layer, a composite layer 222 simulates human
17 skin. For the purposes of this description, skin is considered a membranous layer. Composite
18 layer 222 includes a silicone blend 202 and a reinforcing silicone-coated fibrous layer 204, and
19 preferably a pigment. As is generally known in the elastomer arts, any of a number of suitable
20 pigments for silicone blends can be used to visually represent different layers. The silicone used in
21 the invention is preferably obtained from Silicones, Inc. of High Point, North Carolina, under the
22 mark XP-153A. Preferably, the silicone is mixed with a thinning agent, also obtained from Silicones,
23 Inc., under the mark GI THINNER™. The volume ratio of silicone to thinner may be adjusted more
24 or less to arrive at a suitable hardness and texture, but preferably, the volume ratio is between about
25 2:1 of silicone to thinner and about 10:1 of silicone to thinner. Techniques for molding and curing
26 items of silicone and thinner are generally known by those of ordinary skill in the art and need not be
27 set forth herein to enable the present invention. Although silicone has been found to perform best,
28 other elastomeric materials, such as latex, may alternatively be used. Silicone-coated fibrous
29 layer 204 is preferably pre-formed and cured and is then applied below or atop an uncured silicone
30 formulation while in the mold. As the silicone formulation cures, the pre-formed fibrous layer is

1 bonded thereto. However, the silicone-coated fibrous layer need not be bonded to the silicone blend
2 layer. The silicone-coated fibrous layer 204 imparts a realistic resistance to cutting, similar to the
3 resistance of real human skin. The fibrous layer is preferably made of a nylon mesh material.
4 However, a felt material will perform equally well under some circumstances. Any number of
5 synthetic or natural fibers will also be effective for use in this layer, to some degree. For instance, in
6 the abdomen area, felt is the preferred fibrous material for the silicone-coated fibrous layer. While
7 the skin is intended to be a very close approximation to actual human skin, it is to be recognized that
8 real human skin includes numerous strata of virtually imperceptible differences. However, the
9 simulated skin of the present invention closely represents the epidermis and dermis of actual human
10 skin. Preferably, a pigment is added in the silicone blend to color the skin similar to human skin.
11 Also, composite skin layer 222 including the fibrous layer 204 is about 2 to about 4 millimeters thick.
12 While a preferred embodiment of skin layer 222 includes a reinforcing silicone-coated fibrous
13 layer 204, the ~~user~~ use of more reinforcing layers are contemplated.

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15 On Page 26, the paragraph beginning at line 16 should be replaced with the following.

16 Referring to FIGURE 5, in the area of the neck region, surgical trainer 100 also includes a
17 simulated thyroid cartilage 142, a simulated cricoid cartilage 144, and a simulated cricothyroid
18 ligament 146. Cricoid cartilage 144 and thyroid cartilage 142 are molded of suitable thermoplastic or
19 polymeric materials. Preferably, a rubber such as POLY-FAST 72-40 RTV™ liquid rubber,
20 available from the Polytek Development Corporation of Easton, Pennsylvania can be used to
21 fabricate these pieces. In FIGURE 9, a more detailed view of these structures is shown. These
22 structures form part of the respiration system and include a trachea, modeled here by a plastic
23 tube 148 of similar consistency and resistance to cutting, as exhibited by an actual human trachea.
24 Trachea 148 is connected to the cricoid cartilage 144, which is thicker and stronger than thyroid
25 cartilage 142. Thyroid cartilage 142 is the largest of the laryngeal cartilages (others have been
26 omitted for clarity) and includes a laryngeal prominence 150, better known as the Adam's Apple, and
27 the thyroid notch. In a trainer modeled after a female, the laryngeal prominence will be almost
28 imperceptible. Cricothyroid ligament 146 is represented in this Figure as being integral with the
29 trachea member, but in a human, actually connects the cricoid cartilage 144 and thyroid cartilage 142.
30 The cricothyroid ligament is modeled by a suitable plastic tubing or hose of similar consistency and

1 resistance to cutting as an actual human cricothyroid ligament. The thyroid and cricothyroid
2 cartilages are modeled from a unitary molded piece, which has an aperture traversing longitudinally
3 along the mid axis, so as to fit through trachea 148.

4
5 On Page 31, the paragraph beginning at line 4 should be replaced with the following.

6 Trainer 100 also enables a trainee to practice pericardiocentesis. Pericardiocentesis is another
7 trauma procedure usually done to evaluate the status of a chronic or recurrent pericardial effusion
8 (fluid in the pericardial sac), as a result of trauma to the chest. It may also be done to relieve cardiac
9 tamponade (compression of the heart from an accumulation of fluid within the pericardial sac). The
10 procedure includes the steps of puncturing the skin 1- 2 centimeters inferior and to the left of the
11 xiphochondral junction, at a 45 degree angle to the skin. The needle is advanced ~~cephalad~~ cephalad,
12 aimed toward the tip of the left scapula. When the needle tip enters the blood-filled pericardial sac
13 (pericardium), blood within the pericardial sac can be withdrawn. This part of the procedure is
14 simulated in trainer 100 by filling pericardium 162 with simulated blood. A complication of this
15 procedure includes laceration of the myocardium or wall of the heart, which is simulated in
16 trainer 100 by providing simulated heart 164 filled with a different colored simulated blood. If blood
17 from simulated heart 164 is aspirated, the trainee will recognize that the myocardium has been
18 lacerated (or punctured) by the change in blood color. Thus, the trainee can experience this
19 complication resulting if the needle is inserted at the incorrect location. Another complication might
20 be puncturing a lung, which can be simulated on trainer 100, because the trainer provides an
21 inflatable lung 158.

22
23 On Page 36, the paragraph beginning at line 21 should be replaced with the following.

24 In yet another embodiment, a conductor 338a is placed in ~~gap 336 to~~ gap 336 to complete the
25 circuit. With respect to the blood vessels/intestines noted above, rather than physically moving
26 adjacent ends of such a simulated structure so that the opposed ends are coupled together,
27 conductor 338a represents an additional section of a blood vessel or an intestine that is placed in the
28 gap (and sutured or otherwise coupled to the other portions of the simulated physiological structure)
29 to complete the circuit. In some embodiments, conductor 338a is a probe or instrument, that when
30 properly employed in a simulated medical procedure will complete the circuit. For embodiments in

1 which conductor 338a is a probe or instrument (as opposed to a portion of a simulated physiological
2 structure), the configuration of conductor 338a depends on the simulated medical procedure to be
3 evaluated. In such cases, conductor 338a can be any metallic medical instrument, such as a syringe
4 needle or a scalpel.

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6 On Page 39, the paragraph beginning at line 3 should be replaced with the following.

7 FIGURE 11A schematically illustrates an evaluation circuit 344 that includes a pressure
8 sensitive transducer 343, which as will be described in greater detail below, can be beneficially
9 incorporated into a simulated physiological structure. Such piezoelectric circuits are well known and
10 generate an electrical potential in response to applied mechanical force. Evaluation circuit 344 is
11 configured so that when a probe 338d is utilized to properly execute a simulated medical procedure
12 (and in doing so, applies a force to pressure sensitive transducer 343), an electrical current is
13 generated that can be used to produce a feedback signal indicative of the level of pressure applied.
14 Note that while piezoelectric materials are not elastomeric, a portion of circuit 344 is formed of
15 conductive elastomers. As discussed above, elastomeric materials can be employed to realistically
16 simulate many physiological elements, such as skin, tissue, membranes, fat, muscle ~~an~~ and organs.
17 Piezoelectric materials are generally hard. There are physiological elements that can be simulated
18 using hard materials, such as bone and cartilage. Thus, one implementation of circuit 344 could be a
19 simulated bone, with piezoelectric material simulating a portion of the bone structure, and conductive
20 elastomers simulating muscle and other tissue attached to and disposed adjacent to the bone.
21 However, the force can be transmitted using a fluid, so that the tactile sensation associated with
22 applying the force does not correspond to the feel of a relatively hard pressure sensitive transducer.
23 Thus, if the simulated medical procedure being evaluated is manual cardiac massage, a pressure
24 sensor sensing a pressure of a fluid in the simulated heart can produce the feedback signal indicative
25 of the applied pressure, to indicate if the person applying the pressure to the simulated heart is
26 performing the procedure properly and within acceptable limits. Also, other types of pressure
27 transducers, such as variable capacitance and variable resistance transducers, are available that are
28 less detectable by touch and can be used for sensing applied force or pressure.

29
30 On Page 41, the paragraph beginning at line 22 should be replaced with the following.

FIGURE 11E illustrates a conductive elastomer-based evaluation circuit 361 that includes a capacitance sensitive switch 363. In a capacitance sensitive switch, an inherent or baseline charge of a capacitor is changed. Depending on the configuration of the capacitance sensitive switch, the baseline charge can be changed by a conductive object (which adds or removes charge from the capacitance sensitive switch), or by a non conductive object that changes the properties of the dielectric in the capacitor. Capacitance sensitive switches or sensors can be configured in several ways. In some configurations, at least one of the two electrodes of a capacitor are movable, and the sensor/switch responds to the increase or decrease of the dielectric gap between the electrodes (which changes the baseline charge of the capacitor). In other configurations the positions of the electrodes are fixed, and a nonconductive material is introduced into the dielectric gap between the electrodes, which changes the properties of the dielectric gap, again resulting in a change from the baseline charge of the capacitor. In yet another configuration, the positions of the electrodes are fixed, and a conductive material is placed in contact with one of the plates, yet again changing the baseline state of the capacitor. Thus depending on the configuration of capacitance sensitive switch 363, probe 365 can be a conductor or an insulator. Note that capacitance can be used to measure pressure, as well as responding to touch. As described above, when the dielectric gap between two plates of a capacitor changes, the change in capacitance can be measured. A pressure sensitive circuit can be configured such that as pressure is applied to one plate of a capacitor by a simulated instrument, that plate moves relative to the other plate of the capacitor, effectively changing the baseline capacitance of the capacitor by changing the dielectric gap. The more pressure is applied, the smaller the gap becomes, and the larger the change. Of course, the simulated instrument must be an insulator, or contact by the instrument to the capacitor plate will in and of itself change the baseline capacitance. To respond to pressure applied by a user's fingers or a conductive simulated instrument, an insulator layer (for example, a non conductive elastomeric layer of sufficient thickness to block induction) can be placed between the movable capacitor plate and a trainee's finger or the conductive simulated surgical instrument. Because capacitance sensitive circuits measure the change in capacitance, and capacitance can be changed based on a function of a distance between a capacitor and an object affecting the baseline charge of the capacitor, capacitance sensitive switches/sensors can be used to determine proximity. For example, as a simulated instrument is brought closer and closer to a capacitance sensitive circuit, the change in the baseline capacitance increases. Such capacitance

1 sensitive circuits can be used to determine the degree of proximity between the circuit and an object.
2 Such capacitance sensitive circuits are therefore very useful in enabling a conductive elastomer-based
3 evaluation circuit to provide feedback about the proximity (and the degree of proximity) of an object
4 relative to the circuit. As with resistance sensitive switches, capacitance sensitive switches have also
5 been used to determine a coordinate position in touch sensitive display implementations. When a
6 user touches such a touch sensitive display, some of the charge from the display is transferred to the
7 user, so the charge on the capacitive layer decreases. This decrease is measured in circuits located at
8 each corner of the display. A computer calculates, from the relative differences in charge at each
9 corner, exactly where the touch event took place. If desired, such a position sensitive capacitance
10 sensitive switch can be implemented in a conductive elastomer-based evaluation circuit in accord
11 with the present invention. As discussed above, portions of circuit 361 may be implemented using
12 conventional circuit elements. To achieve a realistic model, preferably portions of circuit 361 that
13 can be seen or felt by a trainee will be implemented using conductive elastomers, to enhance the
14 training experience.

15
16 On Page 43, the paragraph beginning at line 15 should be replaced with the following.

17 As noted above, FIGURES 12A-12D schematically illustrate different embodiments for
18 utilizing the current flowing in the circuits described above to provide feedback indicative of ~~the~~
19 whether a simulated medical procedure is being properly performed, or indicative of the quality of
20 the performance. In FIGURE 12A, an electrical current flowing in the evaluation circuit is used to
21 energize a light source 346a comprising indicator 334. The light source can be a light emitting diode
22 (LED) or other type of light emitting device or lamp. A LED or other solid state light source is
23 preferable, since such devices require less electrical power than do conventional incandescent light
24 sources.

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26 On Page 43, the paragraph beginning at line 24 should be replaced with the following.

27 In FIGURE 12B, indicator 334 comprises a circuit 348, which includes a power source 350, a
28 light source 346b, and an electronic switch 352, which is used to open and close circuit 348.
29 Electronic switch 352 is normally in an open state, and thus, light source 346b is not illuminated.
30 When the evaluation circuit provides a potential to trigger electronic switch 352, the electronic switch

1 changes to a closed state, completing circuit 348 and causing the light source to produce light. Light
2 source 346b is an LED, or lamp. Note that light source 346b can be an incandescent source or other
3 higher current light emitting device without requiring that the evaluation circuit carry the current
4 needed to energize the light source, because light source 346b in circuit 348 is energized by separate
5 power source 350. Of course, electronic switch 352 can be configured to be in the closed state until a
6 trigger potential is received from the evaluation circuit, so that the light source remains energized
7 until the evaluation circuit produces a potential indicative of the proper execution of a simulated
8 medical procedure.

9
10 On Page 46, the paragraph beginning at line 24 should be replaced with the following.

11 Each of conductive elastomers 374, 376, and 378 is coupled to a different light source.
12 Conventional wire conductors can be used for this purpose, or smaller segments of conductive
13 elastomers. Conductive elastomer 378 is coupled to a green light 380a, conductive elastomer 376 is
14 coupled to an amber light 380b, and conductive elastomer 374 is coupled to a red light 380c. Each
15 conductive elastomer is labeled R, A, or G to indicate the color of light to which the conductive
16 elastomer is electrically coupled. The other terminal of each light 380a-380c is then electrically
17 coupled to one terminal of a battery 370. An opaque elastomeric layer 379 is placed over each
18 conductive elastomer, so that the individual conductive elastomers ~~were~~ are not visibly apparent.

19
20 On Page 47, the paragraph beginning at line 20 should be replaced with the following.

21 It should be understood that it would be straightforward to modify circuit 368 to include
22 discrete conductive elastomers that are shaped as vertical strips (like conductive elastomer 378) for
23 monitoring more regions along the X-axis. Thus, the vertical portions of conductive elastomers 374
24 and 376 to the left of conductive elastomer 378 would represent discrete conductive elastomers that
25 monitor corresponding regions, and the vertical portions of conductive elastomers 374 and 376 to the
26 right of conductive elastomer 378 would similarly represent discrete conductive elastomers that
27 monitor corresponding discrete regions along the X-axis. Each individual discrete conductive
28 elastomer would be coupled to a light source of a different color (or to lights in different
29 corresponding positions along an array of light sources – not shown), so that the light source would
30 indicate whether the probe was placed to the left or right of the correct position along the X-axis (i.e.

1 to the left or right of conductive elastomer 378), and the extent of the deviation from the correct
2 position. Of course, instead of coupling each conductive elastomer to a light, the elastomers can be
3 connected to a different indicator, such as a meter, or a computing device or processor that keeps
4 track of which conductive elastomer is contacted by the energized probe. It should also be
5 understood that multilayer configurations with conductive elastomer bars extending horizontally can
6 be used to determine the accuracy of the probe penetration along the Y-axis, and thus the
7 configuration of circuit 368 merely represents one potential embodiment. Any configuration of
8 conductive elastomers employed for a commercial application of the present invention will be
9 selected to evaluate specific simulated medical procedures. Thus, the specific configuration of the
10 evaluation circuit will depend on the simulated procedure ~~be~~ being evaluated, and the simulated
11 physiological structure with which the evaluation circuit is employed. Several examples are
12 described below.

13
14 On Page 60, the paragraph beginning at line 1 should be replaced with the following.

15 Simulated bone 432 includes a fragment 436a separable from a remainder 436b. A procedure
16 often employed to rejoin a fragment to the remainder is to drill a hole passing through the fragment
17 and into the remainder, and to insert a rod or screw into the hole to join the fragment to the remainder
18 ~~together~~ while the ~~bodies'~~ body's healing processes fuse the fragment and remainder together.
19 Simulated bone 432 thus includes an evaluation circuit 438, configured to evaluate whether a hole
20 drilled by a person performing the procedure is properly positioned. Conductive elastomers
21 comprising evaluation circuit 438 are disposed along the preferred drill path through the fragment
22 and remainder of the bone and the drill bit completes a circuit (or breaks a circuit) formed by the
23 conductive elastomers to provide an indication that the drill is properly positioned to drill the hole for
24 the rod.

25
26 On Page 77, the paragraph beginning at line 3 should be replaced with the following.

27 Network 512 includes major branches(shown in bold) 512a that are coupled to each smaller
28 portion of the network, and branches 512a are coupled to port 514. Each simulated physiological
29 structure within human patient simulator 510 (i.e., lungs, organs, joints, tissue, etc.) preferably
30 includes conductive elastomer-based evaluation circuits that are coupled to a major branch, so that

1 feedback from the structures can be collected via port 514. Port 514 and major branches 512a can be
2 used to provide bi-directional signal flow. In some embodiments, simulated lungs will be coupled to
3 a pump that causes the lungs to inflate and deflate. In other embodiments, servo motors will be
4 incorporated into joints or other simulated ~~structure~~ structures to simulate voluntary and involuntary
5 movements (i.e. blinking, breathing, flushing). Thus, port 514 and major branches 512a can be used
6 to distribute control signals from processor 516 to such controllable components (not separately
7 shown in FIGURE 24). A deluxe human patient simulator includes simulated physiological
8 structures having conductive elastomer-based evaluation circuits, each coupled to network 512, so
9 that data relating to many different types of simulated procedures can be collected and analyzed.